### ORIGINAL ARTICLE

### Ares J. Rosakis · Omprakash Samudrala Demirkan Coker

## Intersonic shear crack growth along weak planes

Received: 13 September 1999 / Reviewed and occerted: 19 November 1999

**Abstract** Classical dynamic fracture theories predict the Rayleigh surface wave speed  $(c_R)$  to be the limiting speed of propagation for mode-I cracks in constitutively homogeneous, isotropic, linear elastic materials subjected to remote loading. For mode-II cracks, propagating along prescribed straight line paths, the same theories, while excluding the possibility of crack growth in the speed regime between  $c_R$  and the shear wave speed,  $c_s$ , do not exclude intersonic  $(c_s < v < c_l)$  crack tip speeds. In the present study, we provide the first experimental evidence of intersonic crack growth in such constitutively homogeneous and isotropic solids, ever recorded in a laboratory setting. Intersonic shear dominated crack growth, featuring shear shock waves, was observed along weak planes in a brittle polyester resin under far-field asymmetric loading. The shear cracks initially propagate at speeds just above  $c_{s}$ and subsequently accelerate rapidly to the longitudinal wave speed  $(c_i)$  of the solid. At longer times, when steady state conditions are attained, they propagate at speeds slightly higher than  $\sqrt{2}c_s$ . The experimental results compare well with existing asymptotic theories of intersonic crack growth, and the significance of the preferred speed of  $\sqrt{2}c_s$  is discussed.

Key words Intersonic fracture · Shear cracks · Crack propagation · Shear shock waves · Limiting speeds · Photoelasticity · Dynamic contact

### Introduction

Under remote loading conditions, in-plane cracks in homogeneous, isotropic, linear-elastic materials containing no preferable (weak) crack paths always propagate with mode-I (opening mode) symmetry conditions existing around their tips. The speed of propagation for such locally mode-I cracks cannot exceed the Rayleigh wave

A.J. Rosakis (💌) · O. Samudrala · D. Coker

Graduate Aeronautical Laboratories,

California Institute of Technology, Pasadena, CA 91125, USA e-mail: rosakis@aero.caltech.edu

speed  $(c_R)$  based on energetic considerations [1]. Moreover, experimentally observed cracktip speeds seldom exceed 40–50% of the Rayleigh wave speed even in the most brittle materials [2, 3]. A variety of explanations ranging from high strains [4] and micro damage zones around the crack-tip [3] to wavy crack paths [5] have been offered to reconcile the discrepancy between the observed terminal speed and the theoretically determined limit.

Washabaugh and Knauss [6] proposed that the observed maximal speed of crack propagation is inherently related to the strength of the material. On the basis of an earlier work by Ravichandar and Knauss [3], they argued that, in amorphous brittle solids a zone of microcracks is generated around a propagating crack tip, which is responsible for significantly reducing the crack speed and eventually inducing crack tip branching. In their experiments, they suppressed the formation of microcracks and the tendency for branching by fabricating weak planes along which cracks were made to propagate under remote, symmetric opening loading conditions. Along these weak planes they reported subsonic (speeds less than the shear wave speed,  $c_s$ ) cracks asymptotically approaching  $c_R$  in the limit of vanishing bond strength. In a laboratory setting, the only experimental observations of intersonic crack tip speeds (speeds between  $c_s$  and the dilatational wave speed,  $c_l$ ) and supersonic crack tip speeds (speeds greater than  $c_1$ ) have been limited to cases where the loading is applied directly at the crack tip. Winkler et al. reported supersonic crack growth along weak crystallographic planes in anisotropic single crystals of potassium chloride, where the crack-tip was loaded by laser induced expanding plasma [7, 8]. At an entirely different length scale, indirect observations of intersonic shear rupture have been reported for shallow crustal earthquakes [9, 10]. Here the fault motion is primarily shear dominated and also the material is not strictly monolithic since preferred weak rupture propagation paths exist in the form of fault lines.

Motivated by the observations of highly dynamic shear rupture during earthquakes, a substantial analytical effort has been made to model the mechanics of both subsonic and intersonic dynamic shear crack propagation. Andrews [11] performed a numerical investigation of a dynamically propagating mode-II (in-plane shear) crack with a slip weakening cohesive zone ahead of the tip. He observed that the terminal rupture speed for a shear crack could be either less than the Rayleigh wave speed or slightly greater than  $\sqrt{2}c_s$  depending on the cohesive strength of the fault plane ahead. Burridge et al. [12] performed an analytical investigation of the same problem and concluded that the speed regime  $c_{s} < \upsilon < \sqrt{2}c_{s}$  (where  $\upsilon$  is the crack tip speed) is inherently unstable, while the speed regime  $\sqrt{2}c_s < \upsilon < c_l$  is stable for intersonic shear crack propagation. Broberg [13] investigated the admissibility of various speed regimes for mode-I and mode-II crack propagation along a prescribed straight line path, based on energy considerations. Since fracture is an inherently energy consuming process, he concluded that the speed regimes in which the crack-tip energy release rate is negative are forbidden. Thus he ruled out the speed regime  $c_R < \upsilon < c_s$  for both mode-I and mode-II cracks, whereas the speed regime  $c_s < \upsilon < c_l$  was found to be forbidden for mode-I cracks only. In mode-II the speed regime  $c_s < \upsilon < c_l$  was found to be permissible according to the above stated criterion. Freund [14] obtained the asymptotic stress and particle velocity fields around a steady state mode-II intersonic crack which was prescribed to propagate along its own plane, in a homogeneous, isotropic, linear-elastic material. He concluded that  $\sqrt{2}c_s$  is the only speed permissible for stable intersonic shear crack growth. Broberg [15, 16] also solved the problem of an intersonic shear crack symmetrically expanding at constant speed from zero initial length. He allowed for a finite process region ahead of the tip and concluded that a shear crack can propagate at all intersonic speeds, except those close to  $c_s$  and  $c_l$ . However, till recently, no direct experimental confirmation of the admissibility of mode-II intersonic crack growth has been reported in the open literature. The very first observations of shear dominated intersonic crack growth along weak planes has been briefly reported by the authors very recently in Science [17]. The complete presentation of our results is given here for the first time.

# Experimental observations of intersonic crack growth

Pursuant with the above observations, we conducted experiments to determine whether mode-II intersonic crack growth can be obtained in laboratory specimens under remote loading. However, in monolithic, pre-notched laboratory specimens subjected to shear loading, it is invariably seen that after initiation from the notch tip the crack does not follow a straight path in line with the notch, but instead kinks and follows the local mode-I direction. To make mode-II crack growth possible, by suppressing kinking, and to simulate the prescribed path constraint of the analysis, we introduced a weak plane ahead of the notch tip in the form of a bond between two identical pieces of isotropic material. The bonding process was chosen carefully so that the constitutive properties of the bond are close to those of the bulk material. Thus we constructed a material system which, although not monolithic, can be considered homogeneous with regard to its linear elastic constitutive description. However, fracture toughness along the bond line is lower, so that the material is inhomogeneous with regard to its fracture properties, while homogeneous with regard to its constitutive behavior. It may be worth noting here that the analytical continuum models discussed above, predicting an allowable intersonic crack speed regime for mode-II cracks, are incapable of distinguishing between constitutively homogeneous and monolithic materials with no preferable crack paths and constitutively homogeneous systems involving preferable crack paths. The notion of inhomogeneity in fracture toughness is not contained in these continuum models which do not feature a fracture criterion.

Our experimental set-up used to investigate dynamic shear crack propagation under impact loading is shown in Fig. 1. Dynamic photoelasticity was chosen for capturing the stress field near the propagating crack tip because of its ability to visualize shear shock waves anticipated by the intersonic crack solutions. Homalite-100, a brittle polyester resin which exhibits stress induced birefringence was chosen for this investigation. The specimens were made by bonding two identical 4 mm thick plates of Homalite as shown in Fig. 1. A polyester resin solution (99.5% by wt) was used for bonding, with methyl ethyl ketone peroxide as hardener (0.4%) and cobalt octate (0.1%) as catalyst. The bond was then cured for 48 hours at room temperature. The thickness of the bond was approximately 20-30 µm. A notch, 25 mm long and 2.3 mm wide, was machined on the upper half of the specimen along the bond line. A notch was chosen as the crack initiation site instead of a pre-crack to prevent the transmission of stress waves into the top half, thus ensuring that the notch tip is loaded under predominantly mode-II conditions. The relevant material properties of Homalite at high strain rates ( $\sim 10^3 s^{-1}$ ) are: Young's modulus, E=5.3 GPa, Poisson's ratio, v=0.35, plane stress longitudinal wave speed,  $c_1=2200 \text{ m/s}$  and shear wave speed,  $c_s=1255 \text{ m/s}$ . The shear strength of bulk Homalite-100 is about 42 MPa, and the shear strength of the bond was varied systematically from 30 to 50% of the strength of the bulk material. This shear bond strength was measured using a conventional Iosipescu shear test fixture. In addition to the above described bonding procedure, a limited number of specimens were bonded by the technique of temperature enhanced surface sintering as described by Washabaugh and Knauss [6]. With this method there is no ambiguity regarding the constitutive homogeneity of the resulting bonded structure.

The specimen was subjected to asymmetric impact loading with a projectile as shown in Fig. 1. The projectile was 75 mm long, 50 mm in diameter and was made of hardened steel. A steel piece was bonded to the specimen at the impact site to prevent shattering and to induce a planar loading wave front. Typical impact velocities used in these experiments ranged from 25 to 35 m/s. The compressive longitudinal wave loads the notch-tip in a predominantly shear mode. The dynamic stress field produced by the loading was recorded using photoelasticity in conjunction with high speed photography. A coherent, monochromatic, plane-polarized, collimated laser beam of 50 mm diameter was transmitted through the specimen. The specimen was placed betwen two circular polarizers resulting in an isochromatic fringe pattern due to stress induced birefringence. Photoelasticity is a common optical technique used in solid mechanics applications which provides real time full field information and the reader is referred to Dally and Riley [18] for further details. The isochromatic fringe pattern is recorded by a rotating mirror type high-speed camera capable of recording 80 frames at framing rates up to 2 million frames per second. An argon-ion laser was used, operating at a wavelength of 514.5 nm (green) in a pulsed mode of 8 ns pulse width. The generation of the isochromatic fringe patterns, which are contours of constant maximum in-plane shear stress ( $\tau_{max}$ ), is governed by the stress optic law,

$$\frac{nF}{h} = 2\tau_{\max} = \sigma_1 - \sigma_2 \tag{1}$$

where *F* is the material fringe constant, *h* is the thickness of the specimen,  $\sigma_1$ ,  $\sigma_2$  are the principal stresses and *n* is the isochromatic fringe order.

**Fig. 1** An illustration of the dynamic photoelasticity setup showing a Homalite-100 specimen being subjected to asymmetric impact by a projectile fired from a high speed gas gun

Fig. 2 Selected sequence of

high speed images, showing the isochromatic fringe pattern around a shear crack initiating from a notch along a weak plane in Homalite-100



Figure 2 shows a selected sequence of isochromatic fringe patterns within a field of view surrounding the notch tip. The time after impact as well as the crack tip speed is shown in each frame. The notch as well as the initial loading pulse are clearly visible in the first frame. The wave front is almost vertical, indicating that the notch is being subjected to predominantly shear loading. In the next frame we see the wave diffraction around the notch-tip and simultaneously observe the stress concentration building up. In the last two frames we can discern a crack propagating dynamically along the interface after initiating from the notch-tip. In Fig. 3, the field of view is located downstream from the notch-tip. In the first frame, we see a crack entering the field of view around which the shape of the isochromatic fringe pattern has changed drastically, and in the next frame we can clearly distinguished two lines radiating from the crack-tip across which the fringe pattern changes abruptly (lines of stress discontinuity). These two lines correspond to the two traveling shear shock waves, which limit the spread of shear waves emanating from the crack-tip as it propagates along the interface. The inclination of the shock waves indicates that the crack-tip has exceeded the shear wave speed of Homalite, and has become intersonic. The fringe pattern around the propagating crack in the last two frames is very similar to that in the previous **Fig. 3** Selected sequence of high speed images, showing the isochromatic fringe pattern around a shear crack propagating along a weak plane in Homalite-100



frame, indicating that the propagating crack has reached a steady state.

Typical crack-tip speed histories for two identical experiments varying only in the position of the field of view are shown in Fig. 4. Crack tip speeds were determined using two methods. In the first method, a second order interpolating polynomial is obtained for every three successive points in the crack length history, which is then differentiated to give the crack speed for the midpoint. In the second method, crack tip speeds for frames in which the shock waves can be clearly distinguished, are obtained by measuring their angle of inclination to the crack faces. The angle of inclination  $\beta$  of the shock waves with the crack faces is related to crack-tip speed through the relation,

$$v = \frac{c_s}{\sin\beta} \tag{2}$$

The variation of the crack-tip speed with crack length obtained using the frist method is shown in Fig. 4(A), whereas that obtained by the second method is shown in 4(B). From Fig. 4 we seen that the initially recorded crack-tip speed is close to the shear wave speed of Homalite (within experimental error of  $\pm 100 \text{ m/s}$ ) beyond which it accelerates (at the order of  $10^8 ms^{-2}$ ), thus becoming intersonic. Thereafter, it continues to accelerate up to the plane stress dilatational wave speed of Homalite, following which it decelerates and ultimately reaches to steady state value of about  $\sqrt{2}$  times the shear wave speed. As seen in Fig. 3, the shock wave angle under steady state conditions reaches an almost constant value around 43° to 45°, corresponding to a crack tip speed slightly higher than  $\sqrt{2}c_s$ . Note that the crack tip speed estimate from the shock wave angle is more accurate compared to that obtained from the crack length history due to the inherent propagation of errors in the differentiation process. It should be recalled here that the speed regime between  $c_R$  and  $c_s$  is forbidden by theory based on energy considerations. For this speed regime, the asymptotic solution predicts radiation of energy away from the crack tip (negative energy release rate), which is not possible on physical grounds. Hence a crack with a smoothly varying crack tip speed cannot pass through this forbidden regime. According to this rationale, a crack will have to jump discontinuously from the sub-Rayleigh regime to the intersonic regime. However, another possibility for generating such intersonic speeds is to bypass this forbidden regime by nucleating a crack from the initial notch that instanta-



**Fig. 4** Evolution of crack speed as the shear crack propagates along a weak plane in Homalite-100. (**A**) From crack length history, (**B**) From shock wave angle (FOV=Field Of View)

neously starts to propagate at a speed above  $c_s$ . Within our experimental time resolution the second scenario seems to be the most probable.

### **Comparison with theory**

Freund [14] obtained a steady state asymptotic solution for the stress and particle velocity fields near a mode-II crack propagating intersonically along a prescribed straight line path in a homogeneous, isotropic, linearelastic material. According to this solution, the dominant term governing the stress state near the crack-tip is of the form [14, 19].

$$\sigma_{ij}(\eta_{1}\eta_{2}) = K_{2}^{*}(t) \left\{ \frac{f_{ij}(\theta_{l}, v)}{r_{l}^{q}} + \frac{g_{ij}(v)}{(-n_{1} - \hat{\alpha}_{s}|\eta_{2}|)^{q}} H(-\eta_{1} - \hat{\alpha}_{s}|\eta_{2}|) \right\},$$
(3)

where  $(\eta_1, \eta_2)$  are the coordinates of a point with respect to a moving cartesian coordinate system attached to the crack-tip (with  $\eta_1$ -axis perpendicular to the crack edge and  $\eta_2$ -axis perpendicular to the plane of the crack),  $f_{ij}(...)$  is a known function of crack tip speed and angular position,  $g_{ij}(.)$  is a function of crack tip speed, H(.) is the Heaviside step-function, q is the singularity exponent given by

$$q(v) = \frac{1}{\pi} \tan^{-1} \frac{4\alpha_l \hat{\alpha}_s}{\left(1 - \hat{\alpha}_s^2\right)^2}$$
(4)

and  $r_l$ ,  $\theta_l$ ,  $\alpha_l$ , and  $\hat{\alpha}_s$ , are defined as follows:

$$r_l = \sqrt{\eta_1^2 + \alpha_l^2 \eta_2^2}, \quad \theta_l = \tan^{-1} \frac{\alpha_l \eta_2}{\eta_l}$$
(5)

$$\alpha_l = \sqrt{1 - v^2 / c_l^2}, \quad \hat{\alpha}_s = \sqrt{v^2 / c_s^2 - 1},$$
(6)

 $K_2^*(t)$  is the intersonic stress intensity factor defined as

$$K_2^*(t) = \lim_{r \to 0} \sqrt{2\pi} r^q \sigma_{12}(r, 0).$$
(7)

From Eqn. 3 we see that the asymptotic solution predicts two traveling waves of strong stress discontinuity attached to the crack-tip and inclined at  $\beta = \tan^{-1}(1/\hat{\alpha}_s) = \sin^{-1}(c_s/\upsilon)$  to the crack faces (see argument of the Heaviside function). The stress field is singular at the crack-tip, and the singularity exponent q is a function of the crack-tip speed. Exponent q increases monotonically from 0 at  $v=c_s$  to a value of  $\frac{1}{2}$  at  $v=\sqrt{2}c_s$ and there after decreases monotonically to 0 at  $v=c_1$ . An immediate implication of this behavior of the singularity exponent is that the dynamic crack-tip energy release rate is identically zero in the intersonic regime, except at  $v = \sqrt{2}c_s$ , where it has a finite value. However, fracture processes essentially involve breaking of bonds and creation of new surfaces, which requires a finite energy flow into the crack-tip. This explains the behavior of the crack-tip speed history in Fig. 4 where we saw the propensity of an intersonic mode-II crack to propagate at a

constant speed of  $\sqrt{2}c_s$  under steady state conditions. The stresses are also singular all along the lines of discontinuity with the same strength of singularity as that of the crack-tip. The crack-tip singularity is thus radiated away from the tip to create two shear shock waves. As one would expect, the existence of infinite stress jumps across these shock waves1 is not feasible and such a prediction is an artifact of the theory of linear elasticity. In real materials, however, this prediction corresponds very well with well defined lines across which large but finite stress jumps occur. The pathology of infinite stress jumps and zero crack-tip energy release rate for an intersonic mode-II crack can be overcome by introducing a process zone of finite size ahead of the tip. Such a solution is given by Samudrala et al. [22]. Figure 5 compares an isochromatic fringe pattern recorded during the experiment (A) with that predicted by the Freund's singular solution (B) and the solution incorporating a Dugdale type cohesive zone (C). Both the experimental and simulated patterns are in good agreement with regard to the prediction of the two shock waves, their inclination to the crack faces as well as the oval shape fo the fringes in front of the tip. The cohesive zone solution also introduces some structure across the shock wave by smearing out the stress jump and eliminating the singularities. However, the experimental fringe pattern is distorted by the stress field generated due to the loading pulse as well as due to crack face frictional contact and subsequent damage, as explained later.

Similar observations have been made with regard to intersonic motion of dislocations and mechanical twins. Indeed, Eshelby [23] and Weertman [24] pointed out that radiation free intersonic motion of a glide dislocation in an isotropic solid is possible at a steady state speed of  $\sqrt{2}c_s$ . Weertman [24], in addition, showed that no such critical speed exists for a climb dislocation. Such a behavior can be expected from the fact that an intersonically propagating steady state mode-II crack can be considered as a superposition of a continuous array of glide dislocations, whereas an intersonically propagating steady state mode-I crack can be considered as a superposition of a continuous array of climb dislocations. A unified continuum approach treating both intersonic cracks and dislocations has been developed by Gao et al. [25]. More recently, Gumbsch and Gao [26] have also been shown that dislocations can glide intersonically within the assumptions of discrete atomistic models. Finally an analytical investigation of the conditions leading to intersonic growth of mechanical twinsis given by Rosakis and Tsai [27].

<sup>&</sup>lt;sup>1</sup> According to the linear elastic idealization these shear shocks are dissipation free [20, 21]. However, in real materials, shock waves are generally dissipative. Indeed, in most of the intersonic regime, where the energy flux directly into the crack-tip is zero, the only energy that is consumed is by the traveling shock waves at the tip vicinity.



**Fig. 5** Enlarged view of the isochromatic fringe pattern around a steady state intersonic shear crack along a weak plane in Homalite-100. Shear shock waves are clearly visible. (**A**) Experimental Pattern, (**B**) Theoretical Prediction based on Freund's singular solution [14] and (**C**) Theoretical prediction based on a Dugdale type cohesive zone model by Samudrala et al. [22] (For all cases  $\beta$ =43° and  $\nu$ =1.37  $c_s$ )

### **Crack face contact zone**

An interesting experimental observation associated with intersonic crack propagation along a weak plane is shown in Fig. 6. This is a post-mortem photograph of the upper half of the test specimen showing an enlarged view of the area near the notch tip. Starting from a finite distance ahead of the notch tip along the crack path, a series of short opening cracks, parallel to each other and inclined to the main shear crack can be observed. All the cracks have initiated on the upper crack-face, propagated a finite distance slightly off-vertical into the upper half of the specimen and subsequently got arrested. Occasionally, a few cracks have gone further. The angle of inclination of these cracks was measured to be approximately 11° from the vertical ( $\eta_2$ -axis).

The initiation, propagation and arrest of these cracks can be observed in real time. Indeed, the high speed images of the isochromatic fringe pattern around the main shear crack-tip contain information about the initiation and the growth of these cracks. A typical photograph in which the phenomenon can be clearly distinguished is shown in Fig. 7. A series of symmetric shadow spots associated with the crack tips originate on the crack face, propagate a finite distance into the upper half of the specimen and arrest subsequently. The centers of all these shadow spots fall on a single straight line inclined at about 23° to the crack face. From this measure, a well as the small inclination of these cracks from the vertical, an estimate of their propagation speed is obtained to be 0.6  $c_s$ . The symmetric nature of the shadow spots reveals the opening mode-I nature of these secondary cracks. Further evidence of their subsonic nature can be seen in the epicycloidal shape of the shadow spots surrounding their crack-tips. If we extend the line passing through the center of the shadow spots to the crack face, we can readily see that they originate a finite, albeit a small distance behind the main crack-tip. Hence, formation of these secondary cracks is not akin to the typical branching phenomenon observed in high speed subsonic crack propagation. These secondary, subsonic, opening mode cracks behind the main intersonic shear crack-tip cannot be explained completely based on the asymptotic solution for a traction free intersonic crack. The stress component  $\sigma_{11}$ (direct stress parallel to the crack faces) is tensile in the top half of the specimen, whereas it is compressive in the bottom half. This explains why the opening cracks are observed only in the tensile half of the specimen. If the cracks originated on a traction free surface, we would expect them to propagate vertically based on a maximum principal stress criterion for brittle fracture. The inclination of the secondary cracks from the vertical can only be explained in terms of a more complex state of stress at the initiation site. It is conjectured that crack faces come into contact once the crack-tip exceeds the Rayleight wave speed of the material. Evidence of contact can be seen in Fig. 7, where a near vertical line of discontinuity emanating from the contact zone can be seen across which the fringe pattern changes abruptly. A simi**Fig. 6** Photograph of the area around the notch tip in the tensile half of the specimen showing the secondary cracks inclined at 11° to the vertical



Fig. 7. (A) Enlarged view of the region behind the main intersonic shear crack tip showing the shadow spots associated with the subsonic secondary cracks originating from the contact zone. (B) Schematic showing the initiation and propagation of the tensile secondary cracks and the 2-D stress state on the contact face

lar phenomenon was observed during intersonic crack propagation along a bimaterial interface [21, 28-30]. Due to frictional sliding of the contact faces a twodimensional state of stress exists at the crack faces along the contact zone (the secondary crack initiation site), which explain the 11° inclination of the crack propagation path from the vertical. Assuming a linear frictional contact model ( $\sigma_{12} = \lambda \sigma_{22}$ ), with a constant dynamic coefficient of friction  $\lambda$ , and further postulating that tensile failure will follow the predictions of the maximum principal stress fracture criterion, we can obtain bounds for  $\lambda$ . For a subsonic opening crack of propagate along the principal plane, the nature of the maximum principal stress should be tensile. A simple Mohr's circle analysis gives a lower bound for  $\lambda$  as 0.19. If we further assume that the stress component  $\sigma_{11}$  in the upper half of the specimen is tensile, the lower bound on  $\lambda$  is raised on 0.21. If in addition,  $|\sigma_{11}| > |\sigma_{22}|$  then  $\lambda > 0.4$ . A precise estimate for  $\lambda$  can be obtained if a more elaborate model of intersonic shear crack growth, which includes crack face frictional contact, is developed.

### **Concluding remarks**

To the authors' knowledge, this article describes the first experimental observation of shear-dominated intersonic crack growth. We saw that intersonic crack propagation is possible along a weak plane in a homogeneous material (homogeneous with respect to its constitutive properties, but inhomogeneous with respect to its fracture toughness) subjected to far-field mode-II (in-plane shear) loading conditions. The lower fracture thoughness along the weak plane makes it a preferred path for crack propagation by suppressing kinking and branching, thus ensuring that the crack propagates under mode-II conditions. However, in a purely homogeneous material (homogeneous with respect to both constitutive and fracture properties) with no preferred paths for crack propagation, a mode-II crack immediately after initiation, kinks in the local direction of maximum energy release rate which is nearly coincident with the local mode-I direction [31]. The competition between kinking, in a locally opening mode, and straight-ahead propagation, in a primarily shear mode, can be biased towards a shear, straightahead propagation by artificially reducing the fracture toughness along the preferred path. Moreover, mode-II conditions near a propagating crack-tip are found to be necessary in achieving intersonic crack-tip speeds. Washabaugh and Knauss [6] in their mode-I experiments observed that no matter how weak the crack propagation path is, a mode-I crack never exceeds the Rayleigh wave speed of the material. This observation is supported by the asymptotic solution, which predicts a radiation of energy (negative unbounded energy release rate) away from the crack-tip during mode-I intersonic crack propagation [13], thus excluding this crack growth scenario. However, intersonic shear cracks are found to theoretically have a non-negative energy release rate thus allowing the possibility of intersonic mode-II growth as confirmed experimentally in this article.

Dynamic shear crack propagation is of primary interest in modeling earthquake source dynamics. Analysis of farfield wave forms generated by shallow crustal earthquakes indicates that the source process represents a sudden stress drop across a rupture front, similar to a crack. Furthermore, the high pressures and temperatures deep inside the earth's crust rule out the existence of tensile cracks, allowing for shear cracks only [32–34]. The elastodynamic shear crack model provides an adequate approximation of the source process as a shear rupture along a preexisting weak fault plane whose function is equivalent to the weak bond line in our experiments. Average rupture speeds inferred for most of the shallow crustal earthquakes observed so far range from 0.7 to 0.9  $c_s$ . Rupture propagation is very sensitive to the properties of the surrounding material and as such is a highly transient process. For average rupture velocities close to the shear wave speed, it is plausible that locally, for short durations, rupture speeds could be intersonic. Archuleta [9] and Olsen et al. [10] suggested intersonic rupture speeds based on the analyses of the strong motion data recorded during the 1979 Imperial valley earthquake and the 1989 Landers earthquake respectively. Moreover, numerical studies on propagation of in-plane shear cracks by Das and Aki [35] as well as Andrews [11] have shown that depending on the strength of the fault plane, propagation speeds can be either sub-Rayleigh or intersonic. Indeed our current experiments have convincingly shown that intersonic rupture speeds are possible for shear cracks propagating along a weak plane.

In an analogous situation, cracks along interfaces in bimaterials composed of solids with strong wave speed mismatch have been observed to propagate at speeds that are intersonic with respect to the solid that has the lower wave speeds [28, 29]. However, such cracks were never observed to become intersonic with respect to both solids. Again in this case, interfacial cracks initiated under predominantly shear loading reached intersonic speeds. Here, the bimaterial bond (irrespective of its strength) acts as a preferred crack propagation direction. In yet another material system which exhibits preferred crack propagation directions, intersonic crack growth was observed in unidirectional fiber-reinforced composites under shear dominated loading conditions [36, 37]. Here again, the fiber/matrix interface provides a weak plane which facilitates shear dominated crack propagation.

To summarize, the essential requirement for intersonic crack growth is the existence of mode-II conditions near

the propagating crack-tip. One way to ensure that a propagating crack-tip remains under mode-II conditions is to introduce a weak plane along the preferred crack path. Under such circumstances, a mode-II crack, immediately after initiation, can start to propagate at intersonic speeds and when it does so, it features the formation of shear shock waves emitted from the propagating shear crack tip and large scale crack face frictional contact.

Acknowledgements The authors would like to acknowledge the support of the National Science Foundation (Grant #CMS9813100) and the Office of Naval Research (Grant #N00014-95-1-0453). A.J. Rosakis would also like to thank Prof. J.R. Rice of Harvard University for penetrating discussions during his November 1998 visit to Harvard. Helpful comments by B. Broberg of the university of Lund are also gratefully acknowledged.

#### References

- 1. Freund LB (1990) Dynamic Fracture Mechanics, Cambridge Univ. Press, Cambridge
- 2. Cotterell B (1965) Appl Mat Res 4:227
- 3. Ravichandar K, Knauss WG (1984) Int J Fract 26:141
- 4. Broberg KB (1964) J Appl Mech 31:546
- 5. Gao H (1993) J Mech Phys Solids 1:457
- 6. Washabaugh PD, Knauss WG (1994) Int J Fract 65:97
- 7. Winkler S, Shockey DA, Curran DR (1970) Int J Fract 6:151
- 8. Curran DR, Shockey DA, Winkler S (1970) Int J Fract 6:271
- 9. Archuleta RJ (1982) Bull Seis Soc Am 72:1927
- 10. Olsen KB, Madariaga R, Archuleta RJ (1997) Science 278:834
- 11. Andrews DJ (1976) J Geophys Res 81:5679
- 12. Burridge R, Conn G, Freund LB (1979) J Geophys Res 83:2210
- 13. Broberg KB (1989) Int J Fract 39:1
- 14. Freund LB (1979) J Geophys Res 84:2199
- 15. Broberg KB (1994) Geophys J Int 119:706
- 16. Broberg KB (1995) Arch Mech 47:859
- 17. Rosakis AJ, Samudrala O, Coker D (1999) Science 284:1337
- Dally JW, Riley WF (1991) Experimental Stress Analysis, McGraw-Hill, New York
- 19. There is a typographical error in the expression for  $g_{ij}(v)$  and q as given in [14]. The correct expression can be deduced from the orthotropic solution given in [37]
- 20. Abeyaratne R, Knowles JK (1990) J Mech Phys Solids 38:345
- 21. Liu C, Huang Y, Rosakis AJ (1995) J Mech Phys Soldis 43:189
- Samudrala Ö, Huang Y, Rosakis AJ (1999) Caltech SM Report, 99–11
- 23. Eshelby JD (1949) Proc Roy Soc Lond 62A:307
- Weertman J (1969) Mathematical Theory of Dislocations. Mura J (ed) ASME, New York, 178–202
- Gao H, Huang Y, Gumbsch P, Rosakis AJ (1999) J Mech Phys Solids 47:1941
- 26. Gumbsch P, Gao P (1999) Science 283:965
- 27. Rosakis P, Tsai HY (1995) Int J Solids Struct 32:2711
- 28. Lambros J, Rosakis AJ (1995) J Mech Phys Solids 43:169
- Singh RP, Lambros J, Shukla A, Rosakis AJ (1997) Proc R Soc Lond 453A:2649
- 30. Needleman A, Rosakis AJ (1999) J Mech Phys Solids, in press
- 31. Hutchinson JW, Suo Z (1992) Adv Appl Mech 29:63
- 32. Rice JR (1980) In: Boschi E (ed) Physics of Earth's Interior. Amsterdam, p 555
- Dmowska R, Rice JR (1986) In: Teisseye R (ed) Continuum Theories in Solid Earth Physics. Elsevier, p 187
- 34. Das S (1985) Int J Fract 27:263
- 35. Das S, Aki K (1977) Geophys J R Astron Soc 50:643
- Coker D, Rosakis AJ (1999) Caltech SM Report #98-16, submitted to Philosophical Magazine
- Huang Y, Wang W, Liu C, Rosakis AJ (1999) J Mech Phys Solids 47:1893